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## ON HYPERBOLIC AND TRIGONOMETRIC B-SPLINES ON EQUALLY SPACED KNOTS

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### Abstract.

The object of the present paper is to show that hyperbolic and trigonometric splines admit bases of  $B$ -splines characterized by convolution processes of exponential and trigonometric functions, respectively.

### 1. Introduction

Among the various classes of splines, the polynomial spline has been received the greatest attention primarily because it admits a basis of  $B$ -splines which are accurately and efficiently computed. Recently it has been shown that trigonometric and hyperbolic splines also admit bases of  $B$ -splines ([1], [3]).

The object of the present paper is to show that these  $B$ -splines on equally spaced knots are characterized by a convolution process of exponential function. Throughout this paper, we assume that  $m (\geq 1)$  is a natural number and  $\lambda$  is a positive parameter. Then, by use of  $\phi_\lambda$ :

$$(1.1) \quad \phi_\lambda(x) = e^{\lambda x} \quad (0 \leq x \leq 1) \quad \text{and} \quad 0 \quad (\text{otherwise}),$$

we may define hyperbolic  $B$ -splines:

$$(1.2) \quad \begin{aligned} Q_{2m-1, \lambda}(x) &= (\chi * \phi_\lambda * \phi_{-\lambda} * \dots * \phi_{(m-1)\lambda} * \phi_{-(m-1)\lambda})(x) \\ Q_{2m, \lambda}(x) &= (\phi_{\frac{1}{2}\lambda} * \phi_{-\frac{1}{2}\lambda} * \dots * \phi_{(m-\frac{1}{2})\lambda} * \phi_{-(m-\frac{1}{2})\lambda})(x) \end{aligned}$$

where  $\chi(x) = \lim_{\lambda \rightarrow 0} \phi_\lambda(x)$ . i. e.,  $\chi$  is a characteristic function on  $[0, 1)$ , and for  $f(x)$  and  $g(x)$  we denote

$$\int_{-\infty}^{\infty} f(t) g(x-t) dt \quad \text{by} \quad (f * g)(x).$$

For the polynomial  $B$ -spline  $Q_m(x)$  of degree  $m-1$ , it is well-known that

$$(1.3) \quad Q_m(x) = \underbrace{(\chi * \chi * \dots * \chi)}_m(x).$$

Therefore we have a relation between the above defined hyperbolic  $B$ -spline  $Q_{m,\lambda}$  and this polynomial one  $Q_m$ :

$$\lim_{\lambda \rightarrow 0} Q_{m,\lambda}(x) = Q_m(x).$$

By the definition of  $Q_{m,\lambda}$ , it may be easily shown that the hyperbolic  $B$ -spline has the following properties similar to those of the polynomial one:

- (i)  $Q_{m,\lambda}(x) \in C^{m-2}(-\infty, \infty)$
- (ii)  $Q_{m,\lambda}(x) = Q_{m,\lambda}(m-x)$
- (iii) the support of  $Q_{m,\lambda} = [0, m]$
- (iv)  $Q_{m,\lambda}(x) > 0$  on  $(0, m)$

$$(iv) \quad \sum_{i=-\infty}^{\infty} Q_{2m-1,\lambda}(x-i) = \prod_{k=1}^{m-1} \left\{ \sinh\left(\frac{1}{2}k\lambda\right) / \left(\frac{1}{2}k\lambda\right) \right\}^2$$

(this equality implies a partition of unity)

$$(vi) \quad \int_{-\infty}^{\infty} Q_{2m-1,\lambda}(x) dx = \prod_{k=1}^{m-1} \left\{ \sinh\left(\frac{1}{2}k\lambda\right) / \left(\frac{1}{2}k\lambda\right) \right\}^2$$

$$\int_{-\infty}^{\infty} Q_{2m,\lambda}(x) dx = \prod_{k=1}^m \left[ \sinh\left\{\left(k-\frac{1}{2}\right)\lambda\right\} / \left\{\left(k-\frac{1}{2}\right)\lambda\right\} \right]^2$$

- (vii) on  $(i, i+1)$  with  $i = 0, \pm 1, \dots$

$$(D^2 - \lambda^2)(D^2 - (2\lambda)^2) \dots (D^2 - (r\lambda)^2) DQ_{m,\lambda}(x) = 0$$

$$(m = 2r+1, r = 0, 1, \dots)$$

$$(D^2 - \left(\frac{1}{2}\lambda\right)^2) \dots (D^2 - (r - \frac{1}{2})^2 \lambda^2) Q_{m,\lambda}(x) = 0$$

$$(m = 2r, r = 1, 2, \dots)$$

- (viii) for  $s \in \text{Span} \{Q_{m,\lambda}(x-i)\}_{i=-\infty}^{\infty}$ ,

$$(*) \quad \sum_{i=1}^{m-1} Q_{m,\lambda}^{(k)}(m-i) s(i) = \sum_{i=1}^{m-1} Q_{m,\lambda}(m-i) s^{(k)}(i)$$

$$(k = 1, 2, \dots, m-2).$$

The above consistency relation (\*) at  $(m-1)$  consecutive integer points is reduced to the one at  $(m-2)$  integer points if  $m=5, 7, \dots$  and  $2 \leq k \leq m-2$ , by making an alternating sum of (\*) obtained by writing down (\*), subtracting (\*) with  $i$  replaced by  $i+1$ , adding (\*) with  $i$  replaced by  $i+2$  and so on (for this technique, see [2]).

Our next theorem gives important relations for computing the hyperbolic  $B$ -spline  $Q_{m+1, \lambda}$  of degree  $m$  from the hyperbolic  $B$ -spline  $Q_{m, \lambda}$  of degree  $m-1$ :

**Theorem 1.**

$$(1.4) \quad \begin{aligned} \text{(i)} \quad Q_{m+1, \lambda}(x) &= (2/m\lambda) [Q_{m, \lambda}(x) \sinh(\frac{1}{2}\lambda x) \\ &\quad + Q_{m, \lambda}(x-1) \sinh\{\frac{1}{2}\lambda(m+1-x)\}] \\ \text{(ii)} \quad Q'_{m+1, \lambda}(x) &= Q_{m, \lambda}(x) \cosh(\frac{1}{2}\lambda x) \\ &\quad - Q_{m, \lambda}(x-1) \cosh\{\frac{1}{2}\lambda(m+1-x)\}. \end{aligned}$$

Letting  $\lambda \rightarrow 0$  in the above relations, we have the well known ones of the polynomial  $B$ -spline:

$$(1.5) \quad \begin{aligned} \text{(i)} \quad Q_{m+1}(x) &= (1/m) \{xQ_m(x) + (m+1-x)Q_m(x-1)\} \\ \text{(ii)} \quad Q'_{m+1}(x) &= Q_m(x) - Q_m(x-1). \end{aligned}$$

Here we remark that our  $B$ -spline defined by the convolution process of the exponential function satisfies the recurrence relations with simpler coefficients than the  $B$ -spline defined by the divided difference (Schumaker [3]). In addition, these  $B$ -splines are different only in their coefficients, and so our  $B$ -splines are also considered to be a basis of the following space  $S$ :

$$(1.6) \quad S = \{s \mid s \in F_m \text{ on } (i, i+1) \text{ with } i = 0, \pm 1, \dots \\ \text{and } s \in C^{m-2}(-\infty, \infty)\}$$

where

$$(1.7) \quad F_m = \begin{cases} \text{Span} \{1, \cosh \lambda x, \sinh \lambda x, \dots, \cosh(r\lambda x), \\ \quad \sinh(r\lambda x)\} \quad (m=2r+1) \\ \text{Span} \{\cosh(\frac{1}{2}\lambda x), \sinh(\frac{1}{2}\lambda x), \dots, \cosh(r-\frac{1}{2})\lambda x, \\ \quad \sinh(r-\frac{1}{2})\lambda x\} \quad (m=2r) \end{cases}$$

Next we shall define the trigonometric  $B$ -spline  $\tilde{Q}_{m, \lambda}(x)$  by replacing  $\lambda$  by  $i\lambda$  in the definition of the hyperbolic  $B$ -spline  $Q_{m, \lambda}(x)$ :

$$(1.8) \quad \tilde{Q}_{m, \lambda}(x) = Q_{m, i\lambda}(x)$$

where  $i = \sqrt{-1}$ .

Let us denote  $(\phi_{i\lambda} * \phi_{-i\lambda})(x)$  by  $\psi_{i\lambda}(x)$ . Then we have

$$(1.9) \quad (i) \quad \psi_{i\lambda}(x) = \psi_{i\lambda}(2-x)$$

$$(ii) \quad \text{the support of } \psi_{i\lambda}(x) = [0, 2]$$

$$(iii) \quad \psi_{i\lambda}(x) = \begin{cases} (1/\lambda) \sin \lambda x & (0 \leq x \leq 1) \\ (1/\lambda) \sin \lambda(2-x) & (1 \leq x \leq 2). \end{cases}$$

Thus it easily follows from the definition of the trigonometric  $B$ -spline that it is real valued and has the properties (i) – (vii) except (iv) of the hyperbolic  $B$ -spline, where  $\sinh$  in (v) and  $-$  in (vi) are to be replaced by  $\sin$  and  $+$ , respectively. For (iv),

$$(1.10) \quad \psi_{ik\lambda}(x) > 0 \quad \text{on } (0, 2) \quad \text{for } 0 < \lambda < \pi/k$$

i. e.,

$$(iv)' \quad \tilde{Q}_{m, \lambda}(x) > 0 \quad \text{on } (0, m) \quad \text{for } 0 < \lambda < 2\pi/(m-1)$$

$$(m=2, 3, \dots)$$

$$(\text{for } m=1, \tilde{Q}_{1, \lambda} = x, \text{ and so the above inequality is trivial}).$$

For the trigonometric  $B$ -spline  $\tilde{Q}_{m, \lambda}$ , we have the following recursion formulas with simple coefficients (c. f. [1]):

**Theorem 2.**

$$(1.11) \quad \begin{aligned} (i) \quad \tilde{Q}_{m+1, \lambda}(x) &= (2/m\lambda) [\tilde{Q}_{m, \lambda}(x) \sin(\frac{1}{2}\lambda x) \\ &\quad + \tilde{Q}_{m, \lambda}(x-1) \sin\{\frac{1}{2}\lambda(m+1-x)\}] \\ (ii) \quad \tilde{Q}'_{m+1, \lambda}(x) &= \tilde{Q}_{m, \lambda}(x) \cos(\frac{1}{2}\lambda x) \\ &\quad - \tilde{Q}_{m, \lambda}(x-1) \cos\{\frac{1}{2}\lambda(m+1-x)\}. \end{aligned}$$

## 2. Proofs of Properties (i) – (viii) and Theorems 1, 2

Since the properties (i) – (viii) of the hyperbolic and trigonometric  $B$ -splines are easily obtained by the definition of them, here we shall only prove the property (v). First, we notice that

$$(2.1) \quad \sum_{i=-\infty}^{\infty} \chi(x-i) = 1.$$

By making a convolution of this equation and  $\psi_{k\lambda}(x) (= (\phi_{k\lambda} * \phi_{-k\lambda})(x))$ ,  $k=1, 2, \dots, m-1$ , we have the desired relation:

$$(2.2) \quad \begin{aligned} \sum_{i=-\infty}^{\infty} Q_{2m-1, \lambda}(x-i) &= (1 * \psi_{\lambda} * \psi_{2\lambda} * \dots * \psi_{(m-1)\lambda})(x) \\ &= \prod_{k=1}^{m-1} \int_0^2 \psi_{k\lambda}(x) dx = \prod_{k=1}^{m-1} \left\{ \int_0^1 \phi_{k\lambda}(x) dx \right\} \left\{ \int_0^1 \phi_{-k\lambda}(x) dx \right\} \\ &= \prod_{k=1}^{m-1} \left\{ \sinh\left(\frac{1}{2}k\lambda\right) / \left(\frac{1}{2}k\lambda\right) \right\}^2. \end{aligned}$$

For the trigonometric  $B$ -spline  $\tilde{Q}_{m, \lambda}$ , similarly we have the property (v) from which follows

$$(2.3) \quad 1 \in \text{Span} \left\{ \tilde{Q}_{2m-1, \lambda}(x-i) \right\}_{i=-\infty}^{\infty}$$

for  $\lambda \neq 2(p/k)\pi$  with  $k=1, 2, \dots, m-1$  and  $p=1, 2, \dots$ .

Now the following lemmas are required to prove Theorem 1.

### Lemma 1.

$$(2.4) \quad \begin{aligned} \prod_{k=1}^{m-1} \left\{ \left(u - \frac{1}{2}i\lambda\right)^2 + \left(k - \frac{1}{2}\right)^2 \lambda^2 \right\} \\ = \{u / (u + im\lambda)\} \prod_{k=1}^m (u^2 + k^2 \lambda^2). \end{aligned}$$

**Proof.** We only have to notice the identity:

$$(2.5) \quad \left(u - \frac{1}{2}i\lambda\right)^2 + \left(k - \frac{1}{2}\right)^2 \lambda^2 = (u - ik\lambda) \{u + i(k-1)\lambda\}.$$

On denoting the left hand side of the above relation in Lemma 1 by  $p_m(\lambda)$ , we have

$$(2.6) \quad \begin{aligned} 1/p_m(\lambda) - 1/p_m(-\lambda) &= -(2m\lambda/iu) / \prod_{k=1}^m (u^2 + k^2 \lambda^2) \\ 1/p_m(\lambda) + 1/p_m(-\lambda) &= 2 / \prod_{k=1}^m (u^2 + k^2 \lambda^2). \end{aligned}$$

**Lemma 2.**

$$(2.7) \quad \begin{aligned} & (iu + \frac{1}{2}\lambda) \prod_{k=1}^{m-1} \{(u - \frac{1}{2}i\lambda)^2 + k^2\lambda^2\} \\ &= \prod_{k=1}^m \{k^2 + (k - \frac{1}{2})^2\lambda^2\} / \{(m - \frac{1}{2})\lambda - iu\}. \end{aligned}$$

**Proof.** We have to notice the identity:

$$(2.8) \quad (u - \frac{1}{2}i\lambda)^2 + k^2\lambda^2 = \{u + i(k - \frac{1}{2})\lambda\} \{u - i(k + \frac{1}{2})\lambda\}.$$

Denoting the left hand side of the above equation in equation in Lemma 2 by  $r_m(\lambda)$ , we have

$$(2.9) \quad \begin{aligned} 1/r_m(\lambda) - 1/r_m(-\lambda) &= 2(m - \frac{1}{2})\lambda / \prod_{k=1}^m \{u^2 + (k - \frac{1}{2})^2\lambda^2\} \\ 1/r_m(\lambda) + 1/r_m(-\lambda) &= -2iu / \prod_{k=1}^m \{u^2 + (k - \frac{1}{2})^2\lambda^2\}. \end{aligned}$$

For any function  $f(x)$  defined on  $(-\infty, \infty)$ , let us denote its Fourier transformation by  $\hat{f}$  (if it exists), i. e.,

$$(2.10) \quad \hat{f}(u) = \int_{-\infty}^{\infty} e^{-iux} f(x) dx.$$

Then, by a simple calculation we have the following two lemmas.

**Lemma 3.** Let  $g(x) = f(x) \sinh(\frac{1}{2}\lambda x) + f(x-1) \sinh\{\frac{1}{2}\lambda(p-x)\}$ .  
Then

$$(2.11) \quad \begin{aligned} \hat{g}(u) &= \frac{1}{2} \{e^{\frac{1}{2}\lambda(p-1)-iu} - 1\} \hat{f}(u - \frac{1}{2}i\lambda) \\ &\quad - \frac{1}{2} \{e^{-\frac{1}{2}\lambda(p-1)-iu} - 1\} \hat{f}(u + \frac{1}{2}i\lambda). \end{aligned}$$

**Lemma 4.** Let  $g(x) = f(x) \cosh(\frac{1}{2}\lambda x) - f(x-1) \cosh\{\frac{1}{2}\lambda(p-x)\}$ .

Then

$$(2.12) \quad \begin{aligned} \hat{g}(u) &= \frac{1}{2} \{e^{\frac{1}{2}\lambda(p-1)-iu} - 1\} \hat{f}(u - \frac{1}{2}i\lambda) \\ &\quad - \frac{1}{2} \{e^{-\frac{1}{2}\lambda(p-1)+iu} - 1\} \hat{f}(u + \frac{1}{2}i\lambda). \end{aligned}$$

Now we are ready to prove Theorem 1. By an elementary calculation,

$$(2.13) \quad \hat{\chi}(u) = -(1/iu)(e^{-iu}-1)$$

$$\hat{\psi}_\lambda(u) = -\{1/(u^2 + \lambda^2)\}(e^{\lambda-iu}-1)(e^{-\lambda-iu}-1).$$

Hence we have

$$(2.14) \quad (i) \quad \hat{Q}_{2m+1,\lambda}(u) = \{(-1)^{m+1}/iu\} \theta_m / \prod_{k=1}^m (u^2 + k^2 \lambda^2)$$

$$(ii) \quad \hat{Q}_{2m,\lambda}(u) = (-1)^m \bar{\theta}_m / \prod_{k=1}^m \{u^2 + (k - \frac{1}{2})^2 \lambda^2\}$$

where

$$(2.15) \quad \theta_m = \prod_{k=-m}^m (e^{k\lambda-iu}-1)$$

$$\bar{\theta}_m = \prod_{k=1}^m (e^{(k-\frac{1}{2})\lambda-iu}-1)(e^{-(k-\frac{1}{2})\lambda-iu}-1).$$

A little additional computation yields

$$(2.16) \quad (e^{m\lambda-iu}-1) \hat{Q}_{2m,\lambda}(u - \frac{1}{2}i\lambda) = (-1)^m \theta_m / p_m(\lambda)$$

$$(e^{-m\lambda-iu}-1) \hat{Q}_{2m,\lambda}(u + \frac{1}{2}i\lambda) = (-1)^m \theta_m / p_m(-\lambda).$$

By Lemma 3 and (2.16), we have

$$(2.17) \quad \hat{Q}_{2m,\lambda}(x) = \sinh(\frac{1}{2}\lambda x) + Q_{2m,\lambda}(x-1) \sinh\{\frac{1}{2}\lambda(2m+1-x)\}$$

$$= \frac{1}{2}(-1)^m \theta_m \{1/p_m(\lambda) - 1/p_m(-\lambda)\}$$

$$= (-1)^{m+1} \{m\lambda \theta_m / iu\} / \prod_{k=1}^m (u^2 + k^2 \lambda^2) = m\lambda \hat{Q}_{2m+1,\lambda}(u).$$

This completes the proof of the recursion formula (i) in Theorem 1 for  $m$  odd.

By a simple calculation, from 2.14(i) we have

$$(2.18) \quad \{e^{(m-\frac{1}{2})\lambda-iu}-1\} \hat{Q}_{2m-1,\lambda}(u - \frac{1}{2}i\lambda) = (-1)^m \bar{\theta}_m / r_m(\lambda).$$

$$\{e^{(m-\frac{1}{2})\lambda-iu}-1\} \hat{Q}_{2m-1,\lambda}(u + \frac{1}{2}i\lambda) = (-1)^m \bar{\theta}_m / r_m(-\lambda).$$

Hence by Lemma 3 and (2.18) we obtain

$$(2.19) \quad \hat{Q}_{2m-1,\lambda}(x) \sinh(\frac{1}{2}\lambda x) + \hat{Q}_{2m-1,\lambda}(x-1) \sinh\{\frac{1}{2}\lambda(2m-x)\}$$



$$\begin{aligned}
&= (-1)^m (m - \frac{1}{2}) \lambda \bar{\theta}_m / \prod_{k=1}^m \{u^2 + (k - \frac{1}{2})^2 \lambda^2\} \\
&= (m - \frac{1}{2}) \lambda \hat{Q}_{2m, \lambda}(u).
\end{aligned}$$

This completes the proof of (i) Theorem 1 for  $m$  even.

Next we shall prove the differentiation formula (ii) in Theorem 1.

Since

$$(2.20) \quad (D\hat{Q}_{2m+1, \lambda})(u) = iu\hat{Q}_{2m+1, \lambda}(u),$$

we get

$$(2.21) \quad (D\hat{Q}_{2m+1, \lambda})(u) = (-1)^{m+1} \theta_m / \prod_{k=1}^m (u^2 + k^2 \lambda^2).$$

On the other hand, by Lemma 4 we have

$$\begin{aligned}
(2.22) \quad &\hat{Q}_{2m, \lambda}(x) \cosh(\frac{1}{2} \lambda x) - \hat{Q}_{2m, \lambda}(x-1) \cosh\{\frac{1}{2} \lambda (2m+1-m)\} \\
&= \frac{1}{2} (-1)^{m+1} \theta_m \{1/p_m(\lambda) + 1/p_m(-\lambda)\} \\
&= (-1)^{m+1} \theta_m / \prod_{k=1}^m (u^2 + k^2 \lambda^2) = (D\hat{Q}_{2m+1, \lambda})(u).
\end{aligned}$$

This completes the proof of (ii) in Theorem 1 for  $m$  odd.

Similarly we have

$$(2.23) \quad (D\hat{Q}_{2m, \lambda})(u) = (-1)^m iu \bar{\theta}_m / \prod_{k=1}^m \{u^2 + (k - \frac{1}{2})^2 \lambda^2\}.$$

On the other hand, by Lemma 4 we have

$$\begin{aligned}
(2.24) \quad &\hat{Q}_{2m-1, \lambda}(x) \cosh(\frac{1}{2} \lambda x) - \hat{Q}_{2m-1, \lambda}(x-1) \cosh\{\frac{1}{2} \lambda (2m-m)\} \\
&= \frac{1}{2} (-1)^{m+1} \bar{\theta}_m \{1/r_m(\lambda) + 1/r_m(-\lambda)\} \\
&= (-1)^m iu \bar{\theta}_m / \prod_{k=1}^m \{u^2 + (k - \frac{1}{2})^2 \lambda^2\}.
\end{aligned}$$

This completes the proof of (ii) in Theorem 1 for  $m$  even.

Now we shall prove Theorem 2. The following two lemmas are required:

**Lemma 5.**

$$\begin{aligned}
 (2.25) \quad & \hat{f}(x) \sin \left( \frac{1}{2} \lambda x \right) + \hat{f}(x-1) \sin \left\{ \frac{1}{2} \lambda (p-x) \right\} \\
 &= \frac{1}{2} i \left\{ e^{-\frac{1}{2} i \lambda (p-1) - iu} \right\} \hat{f}\left(u - \frac{1}{2} \lambda\right) \\
 &\quad - \frac{1}{2} i \left\{ e^{\frac{1}{2} i \lambda (p-1) - iu} - 1 \right\} \hat{f}\left(u + \frac{1}{2} \lambda\right).
 \end{aligned}$$

**Lemma 6.**

$$\begin{aligned}
 (2.26) \quad & \hat{f}(x) \cos \left( \frac{1}{2} \lambda x \right) - \hat{f}(x-1) \cos \left\{ \frac{1}{2} \lambda (p-x) \right\} \\
 &= -\frac{1}{2} \left\{ e^{\frac{1}{2} i \lambda (p-1) - iu} - 1 \right\} \hat{f}\left(u + \frac{1}{2} \lambda\right) \\
 &\quad - \frac{1}{2} \left\{ e^{-\frac{1}{2} i \lambda (p-1) - iu} - 1 \right\} \hat{f}\left(u - \frac{1}{2} \lambda\right).
 \end{aligned}$$

By making use of Lemmas 1, 2, 5 and 6, similarly as in the proof of Theorem 1 we may have Theorem 2.

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### Appendix

In the definition of the hyperbolic  $B$ -spline  $Q_{m, \lambda}$ , we may use an exponential (distribution) function  $\phi_\lambda$ :

$$\phi_\lambda(x) = \begin{cases} \lambda e^{\lambda x} / (e^\lambda - 1) & (0 \leq x < 1) \\ 0 & (\text{otherwise}). \end{cases}$$

Then, since  $\int_{-\infty}^{\infty} \phi_{k\lambda}(x) dx = 1$ ,  $k = \pm 1, \pm 2, \dots$ , the right hand sides of the equations in (v) and (vi) are simply equal to 1. However, in this case the coefficients involved in the recursion formulae in main Theorem 1 are more complicated than before.