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## A Formula in Combinatorics Derived from the Zeta Functions of RLL(m,n) Shift Dynamical Systems

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**Abstract.** In this article we will compute the numbers of periodic points and the zeta functions of RLL(m, n) shift dynamical systems to obtain a formula in combinatorics. We will generalize this formula and prove it directly. It will turn out that the generalized formula is related to the numbers of periodic points of RLL(a<sub>1</sub>, ⋯, a<sub>s</sub>) shift dynamical systems which is a generalization of RLL(m, n) shift dynamical systems.

**Keywords and Phrases.** Number of periodic points of RLL(m,n) shift; Zeta function of Symbolic Dynamical System; A formula in Combinatorics

### 1 Preliminaries

Throughout this paper we will use the notation and terminology in [1]. We begin with recalling a minimum of them. Let  $\mathcal{A}$  be a finite set of symbols which are called the **alphabet**. Elements of alphabet are also called **letters**, and they will typically be denoted by  $\mathbf{a}, \mathbf{b}, \mathbf{c}, \dots$ , or sometimes by digits like  $0, 1, 2, \dots$ .

**Definition 1.1** *If  $\mathcal{A}$  is a finite alphabet, then the full  $\mathcal{A}$ -shift  $\mathcal{A}^{\mathbb{Z}}$  is the collection of all bi-infinite sequences of symbols from  $\mathcal{A}$ , i.e.,*

$$\mathcal{A}^{\mathbb{Z}} = \{ \mathbf{x} = (x_i)_{i \in \mathbb{Z}} \mid x_i \in \mathcal{A} \text{ for all } i \in \mathbb{Z} \}.$$

The **full r-shift** (or simply **r-shift**) is the full shift over the alphabet  $\{0, 1, \dots, r-1\}$ .

When writing a specific sequence in  $\mathcal{A}^{\mathbb{Z}}$ , we need to specify which is the 0-th coordinate. This is conveniently done with a decimal point to separate the  $x_i$  with  $i \geq 0$  from those with  $i < 0$ . For example,

$$\mathbf{x} = \dots 010.1101 \dots$$

means that  $x_{-3} = 0, x_{-2} = 1, x_{-1} = 0, x_0 = 1, x_1 = 1, x_2 = 0, x_3 = 1$ , and so on.

**Definition 1.2** *The shift map  $\sigma$  on the full shift  $\mathcal{A}^{\mathbb{Z}}$  maps a point  $\mathbf{x}$  to the point  $\mathbf{y} = \sigma(\mathbf{x})$  whose  $i$ -th coordinate is  $y_i = x_{i+1}$ .*

A **block** (or **word**) over  $\mathcal{A}$  is a finite sequence of symbols from  $\mathcal{A}$ . It is convenient to include the sequence of no symbols, called the **empty block** (or **empty word**) and denoted  $\varepsilon$ . The **length** of a block  $\mathbf{u}$  is the number of symbols it contains, and is denoted by  $|\mathbf{u}|$ . Thus if  $\mathbf{u} = \mathbf{a}_1 \mathbf{a}_2 \dots \mathbf{a}_k$  is a nonempty block, then  $|\mathbf{u}| = k$ , while  $|\varepsilon| = 0$ . A **k-block** is simply a block of length  $k$ . The set of all  $k$ -blocks over  $\mathcal{A}$  is denoted by  $\mathcal{A}^k$ . If  $\mathbf{x}$  is a point in  $\mathcal{A}^{\mathbb{Z}}$  and  $i \leq j$ , then the block of coordinates in  $\mathbf{x}$  from position  $i$  to position  $j$  is denoted by

$$\mathbf{x}_{[i,j]} = x_i x_{i+1} \dots x_j$$

If  $i > j$ , define  $\mathbf{x}_{[i,j]}$  to be  $\varepsilon$ . If  $\mathbf{x} \in \mathcal{A}^{\mathbb{Z}}$  and  $\mathbf{w}$  is a block over  $\mathcal{A}$ , it is said that  $\mathbf{w}$  **occurs in**  $\mathbf{x}$  if there are indices  $i$  and  $j$  so that  $\mathbf{w} = \mathbf{x}_{[i,j]}$ . Note that the empty block  $\varepsilon$  is in every  $\mathbf{x}$ , since  $\varepsilon = \mathbf{x}_{[1,0]}$ . Let  $\mathcal{F}$  be a collection of blocks over  $\mathcal{A}$ , which is thought of as being the **forbidden blocks**. For any such  $\mathcal{F}$ , define  $X_{\mathcal{F}}$  to be the set of subsequences in  $\mathcal{A}^{\mathbb{Z}}$  which do not contain any block in  $\mathcal{F}$ .

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**Definition 1.3** A **shift space** (or simply **shift**) over  $\mathcal{A}$  is a subset  $X$  of a full shift  $\mathcal{A}^{\mathbb{Z}}$  such that  $X = X_{\mathcal{F}}$  for some collection  $\mathcal{F}$  of forbidden blocks over  $\mathcal{A}$ . If  $\mathcal{F}$  is a finite set, then we call  $X = X_{\mathcal{F}}$  a **shift of finite type**. When a shift space  $X$  is contained in a shift space  $Y$ , we say that  $X$  is a **subshift** of  $Y$ .

**Definition 1.4** Let  $X$  be a subset of a full shift, and let  $\mathcal{B}_n(X)$  denote the set of all  $n$ -blocks that occur in points in  $X$ . The **language** of  $X$  is the collection

$$\mathcal{B}(X) = \bigcup_{n=0}^{\infty} \mathcal{B}_n(X)$$

We consider a map  $\phi$  from a shift space  $X$  over  $\mathcal{A}$  to a shift space  $Y$  over another alphabet  $\mathfrak{A}$  described as follows. Fix integer  $m$  and  $n$  with  $-m \leq n$ . Let  $\Phi : \mathcal{B}_{m+n+1}(X) \rightarrow \mathfrak{A}$  be a fixed map from  $\mathcal{B}_{m+n+1}(X)$ , the set of all  $(m+n+1)$ -blocks to the alphabet  $\mathfrak{A}$ , which is called an  **$(m+n+1)$ -block map** from allowed  $(m+n+1)$ -blocks in  $X$  to symbols in  $\mathfrak{A}$ .

**Definition 1.5** The map  $\phi : X \rightarrow \mathfrak{A}^{\mathbb{Z}}$  defined by  $y = \phi(x)$  with  $y_i$  given by

$$y_i = \Phi(x_{i-m}x_{i-m+1} \cdots x_{i+n}) = \Phi(x_{[i-m, i+n]})$$

is called the **sliding block code with memory  $m$  and anticipation  $n$  induced by  $\Phi$** . We will denote the formation of  $\phi$  from  $\Phi$  by  $\phi = \Phi_{\infty}^{[-m, n]}$ , or simply by  $\phi = \Phi_{\infty}$  if the memory and anticipation of  $\phi$  are understood. If not specified, the memory is taken to be 0. If  $Y$  is a shift space contained in  $\mathfrak{A}^{\mathbb{Z}}$  and  $\phi(X) \subset Y$ , we write  $\phi : X \rightarrow Y$ .

Obviously, if  $\phi : X \rightarrow Y$  is a sliding block code between shift spaces, then  $\phi \circ \sigma_X = \sigma_Y \circ \phi$ , i.e., the following diagram commutes:

$$\begin{array}{ccc} X & \xrightarrow{\sigma_X} & X \\ \phi \downarrow & & \downarrow \phi \\ Y & \xrightarrow{\sigma_Y} & Y, \end{array}$$

where  $\sigma_X$  and  $\sigma_Y$  are the shifts maps of  $X$  and  $Y$ , respectively. If a sliding block code  $\phi : X \rightarrow Y$  has an inverse, i.e., a sliding block code  $\psi : Y \rightarrow X$  such that  $\psi(\phi(x)) = x$  for all  $x \in X$  and  $\phi(\psi(y)) = y$  for all  $y \in Y$ , we call  $\phi$  **invertible**. If  $\phi$  is invertible, its inverse  $\psi$  is unique, so we can write  $\psi = \phi^{-1}$ .

**Definition 1.6** A sliding block code  $\phi : X \rightarrow Y$  is a **conjugacy from  $X$  to  $Y$** , if it is invertible. Two shift spaces  $X$  and  $Y$  are **conjugate** (written  $X \cong Y$ ) if there is a conjugacy from  $X$  to  $Y$ .

**Definition 1.7** A **graph  $G$**  consists of a finite set  $\mathcal{V} = \mathcal{V}(G)$  of **vertices** (or **states**) together with a finite set  $\mathcal{E} = \mathcal{E}(G)$  of **edges**. Each edge  $e \in \mathcal{E}(G)$  **starts** at a vertex denoted by  $i(e) \in \mathcal{V}(G)$  and **terminates** at a vertex  $t(e) \in \mathcal{V}(G)$  (which can be the same as  $i(e)$ ). Equivalently, the edge has **initial state**  $i(e)$  and **terminale state**  $t(e)$ .

There may be more than one edge between a given initial state and terminal state; a set of such edges is called a set of **multiple edges**.

**Definition 1.8** A graph  $G$  is **irreducible** if for every ordered pair of vertices  $I$  and  $J$  there is a path in  $G$  starting at  $I$  and terminating at  $J$ .

**Definition 1.9** Let  $G$  be a graph with vertex set  $\mathcal{V}$ . For vertices  $I, J \in \mathcal{V}$ , let  $A_{IJ}$  denote the number of edges in  $G$  with initial state  $I$  and terminal state  $J$ . Then the **adjacency matrix** of  $G$  is  $A = [A_{IJ}]$ , and its formation from  $G$  is denoted by  $A = A(G)$  or  $A = A_G$ .

**Definition 1.10** Let  $G$  be a graph with edge set  $\mathcal{E}$  and adjacency matrix  $A$ . The edge shift  $X_G$  or  $X_A$  is the shift space over the alphabet  $\mathcal{A} = \mathcal{E}$  specified by

$$X_G = X_A = \{ \xi = (\xi_i)_{i \in \mathbb{Z}} \in \mathcal{E}^{\mathbb{Z}} \mid t(\xi_i) = i(\xi_{i+1}) \text{ for all } i \in \mathbb{Z} \}.$$

The shift map on  $X_G$  or  $X_A$  is called the **edge shift map** and is denoted by  $\sigma_G$  or  $\sigma_A$ .

According to the definition, a bi-infinite sequence of edges is in  $X_G$  exactly when the terminal state of each edge is the initial state of the next one; i.e., the sequence describes a **bi-infinite walk** or **bi-infinite trip** on  $G$ .

**Definition 1.11** A labeled graph  $\mathcal{G}$  is a pair  $(G, \mathcal{L})$ , where  $G$  is a graph with edge set  $\mathcal{E}$ , and the labeling  $\mathcal{L} : \mathcal{E} \rightarrow \mathcal{A}$  assigns to each edge  $e$  of  $\mathcal{E}$ , and a label  $\mathcal{L}(e)$  from the finite alphabet  $\mathcal{A}$ . The **underlying graph** of  $\mathcal{G}$  is  $G$ . A labeled graph is **irreducible** if its underlying graph is irreducible.

**Definition 1.12** A subset  $X$  of a full shift is a **sofic shift** if  $X = X_{\mathcal{G}}$  for some labeled graph  $\mathcal{G}$ . A **presentation** of a sofic shift  $X$  is a labeled graph  $\mathcal{G}$  for which  $X_{\mathcal{G}} = X$ . The shift map on  $X_{\mathcal{G}}$  is denoted by  $\sigma_{\mathcal{G}}$ .

**Definition 1.13** A shift space  $X$  is **mixing** if, for every ordered pair  $u, v \in \mathcal{B}(X)$ , there is an  $N$  such that for each  $n \geq N$  there is word  $w \in \mathcal{B}_n(X)$  such that  $uwv \in \mathcal{B}(X)$ .

For two points  $x, y$  of a full shift  $\mathcal{A}^{\mathbb{Z}}$  over an alphabet  $\mathcal{A}$ , we put

$$(1.1) \quad \rho(x, y) = \begin{cases} 2^{-k} & \text{if } x \neq y \text{ and } k \text{ is maximal so that } x_{[-k, k]} = y_{[-k, k]} \\ 0 & \text{if } x = y. \end{cases}$$

This  $\rho$  satisfies the axioms of a metric, so it makes  $\mathcal{A}^{\mathbb{Z}}$  a metric space. As we can see easily the topology on  $\mathcal{A}^{\mathbb{Z}}$  induced by this metric is equivalent to the product topology of discrete topology on  $\mathcal{A}^{\mathbb{Z}}$ . The discrete topology on a finite set  $\mathcal{A}$  makes it compact. Hence, due to Tikhonov's theorem,  $\mathcal{A}^{\mathbb{Z}}$  with the metric  $\rho$  is also compact. In what follows we always consider this metric on  $\mathcal{A}^{\mathbb{Z}}$ . The shift map  $\sigma$  is a homeomorphism with respect to the topology induced by the metric  $\rho$ , so  $(\mathcal{A}^{\mathbb{Z}}, \sigma)$  can be considered as an **invertible dynamical system** (cf. [1], Definition 6.2.1). A subset  $X$  of  $\mathcal{A}^{\mathbb{Z}}$  is a shift space if and only if it is shift-invariant, i.e.,  $\sigma(X) = X$ , and compact (cf. [1], Theorem 6.1.21). From this fact it follows that any shift space can also be considered as an invertible dynamical system. When we consider a shift space with the metric  $\rho$  in (1.1) as a dynamical system, we call it a **shift dynamical system**. A homeomorphism  $\phi$  from a shift  $(X, \sigma_X)$  to another one  $(Y, \sigma_Y)$  is said to be a **topological conjugacy** if  $\phi \circ \sigma_X = \sigma_Y \circ \phi$ . Two shift spaces are said to be **topological conjugate** if there is a topological conjugacy between them. The fact that two shift spaces are conjugate as a shift space if and only if they are topologically conjugate as a dynamical system follows from the following theorem ([1], Theorem 6.2.9).

**Theorem 1.14 (Curtis-Lyndon-Hedlund Theorem)** Suppose that  $(X, \sigma_X)$  and  $(Y, \sigma_Y)$  are shift dynamical systems, and that  $\theta : X \rightarrow Y$  is a (not necessarily continuous) map. Then  $\theta$  is a sliding block code if and only if it is continuous and commutes with shift maps, i.e.,  $\theta \circ \sigma_X = \sigma_Y \circ \theta$ .

## 2 RLL(m,n) shifts and their characteristic polynomials

For each pair  $(m, n)$  of positive integers with  $m < n$ , we define  $X(m, n)$  to be the set of all binary sequences for all 1's occur infinitely often in  $x$  in both directions, and there are at least  $m$  0's, but no more than  $n$  0's, between two 1's.  $X(m, n)$  is called **(m,n) run-length limited shift**.  $X(m, n)$  is the **sofic shift** associated to the following labeled graph:

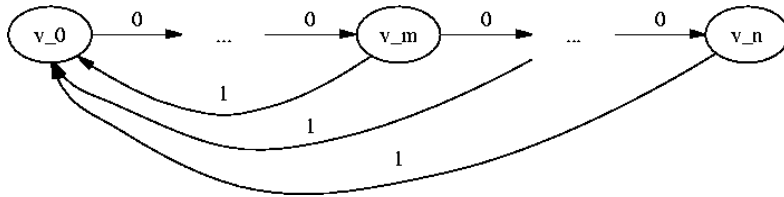
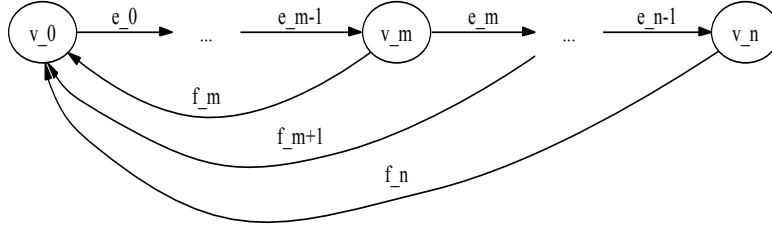


Figure 2.1:  $X(m, n)$

We denote by  $G(m, n)$  the underlying graph of the labeled graph in Figure 2.1. We name each vertex and each edge in  $G(m, n)$  as follows:

Figure 2.2:  $G(m, n)$ 

**Proposition 2.1** *If we put*

$$\mathcal{F} = \left\{ 11, 101, 1001, \dots, 1\underbrace{0 \dots 0}_{m-1}1, \underbrace{0 \dots 0}_{n+1} \right\},$$

*then  $X(m, n) = X_{\mathcal{F}}$ .*

**Proof:** Let  $x$  be a point in  $\mathcal{A}^{\mathbb{Z}}$  where  $\mathcal{A} = \{0, 1\}$ . Assume  $x \notin X_{\mathcal{F}}$ . Then  $x$  must contain a block in  $\mathcal{F}$ , and so  $x \in X(m, n)$ . Hence  $X(m, n) \subset X_{\mathcal{F}}$ . To prove the converse inclusion, we assume  $x \in X_{\mathcal{F}}$ . Then, since the number of consecutive 0's which occurs in  $x$  can not exceed  $n + 1$ , 1 occurs infinitely many times in both directions. If we look at a block  $w$  in  $x$  which has consecutive 0's sandwiched by two 1's like  $10 \dots 01$ , then the number of 0's in the block is more than  $m - 1$  and less than  $n + 1$ . There exists the unique path  $\pi$  in the graph in Figure 2.2 such that  $\mathcal{L}(\pi) = w$  where  $\mathcal{L} : \mathcal{E}(G(m, n)) \rightarrow \{0, 1\}$  is the labeling in Figure 2.1. The path  $\pi$  always ends at the vertex  $v_0$ . Hence, there exists the unique infinite path  $\pi_{\infty}(x)$  in both direction in the graph in Figure 2.2 such that  $\mathcal{L}(\pi_{\infty}(x)) = x$ , that is,  $x \in X(m, n)$ . Therefore  $X_{\mathcal{F}} \subset X(m, n)$ . Consequently,  $X_{\mathcal{F}} = X(m, n)$ . ■

**Proposition 2.2**  *$X(m, n)$  is conjugate to  $X_{G(m, n)}$  as a shift space.*

**Proof:** We will construct a sliding block code  $\phi : X(m, n) \rightarrow X_{G(m, n)}$  which gives a conjugacy between them. As shown in the proof of Proposition 2.1, for any point  $x$  of  $X(m, n)$  there exists the unique infinite path  $\pi_{\infty}(x)$  in both directions in the graph in Figure 2.2 such that  $\mathcal{L}(\pi_{\infty}(x)) = x$ . We define  $\phi(x) = \pi_{\infty}(x)$ . Obviously,  $\phi$  commutes with the shift maps. Furthermore,  $\phi(x)_0$  is a function of  $x_{[-n, n]}$ . To see this fact, argue as follows: If  $x_0 = 1$ , then all of  $x_{-i}$  are zeros for  $1 \leq i \leq n$ , or there exists  $k$  with  $m \leq k \leq n - 1$  such that  $x_{-1} = \dots = x_{-k} = 0$  and  $x_{-(k+1)} = 1$ . In the former case  $\phi(x)_0 = f_n$ , and in the latter case  $\phi(x)_0 = f_k$ . If  $x_0 = 0$ , then there exist  $k$  and  $\ell$  with  $0 \leq k \leq n - 1$ ,  $0 \leq \ell \leq n - 1$  and  $m + 1 \leq k + \ell + 1 \leq n$  such that  $x_{-k+1} = x_{\ell+1} = 1$ ,  $x_{-1} = \dots = x_{-k} = 0$  ( $1 \leq k$ ), and  $x_1 = \dots = x_{\ell} = 0$  ( $1 \leq \ell$ ). In this case  $\phi(x)_0 = e_k$ . In all cases  $\phi(x)_0$  is decided by  $x_{[-n, n]}$ , which means that  $\phi(x)_0$  is a function of  $x_{[-n, n]}$ . Therefore  $\phi$  is a sliding block code ([1], Proposition 1.5.8). The map  $\psi : X_{G(m, n)} \rightarrow X(m, n)$  defined by  $\psi(\pi_{\infty}) = \mathcal{L}(\pi_{\infty})$  for  $\pi_{\infty} \in X_{G(m, n)}$  gives the inverse of  $\phi$ , so  $\phi$  gives a conjugacy between  $X(m, n)$  and  $X_{G(m, n)}$ . ■

**Proposition 2.3**  *$X(m, n)$  is mixing.*

**Proof:** We consider  $X_{G(m, n)}$  instead of  $X(m, n)$  due to Proposition 2.2. In  $X_{G(m, n)}$  there are periodic points of period  $m + 1$  and  $m + 2$ . Since  $m + 1$  and  $m + 2$  are co-prime,  $\text{per}(X_{G(m, n)}) = 1$ , where  $\text{per}(X_{G(m, n)})$  is the greatest common divisor of the periods of  $X_{G(m, n)}$ 's periodic points. Obviously,  $X_{G(m, n)}$  is irreducible. Therefore we can conclude that  $X_{G(m, n)}$  is mixing ([1], Proposition 4.5.10). ■

In what follows we always consider  $X_{G(m, n)}$  instead of  $X(m, n)$ . The adjacency matrix of the graph  $G(m, n)$  denoted by  $A(m, n)$  is as follows:

$$\begin{array}{c}
v_0 \quad v_1 \quad \cdot \quad v_{m-1} \quad v_m \quad \cdot \quad \cdot \quad \cdot \quad v_n \\
v_0 \\
v_1 \\
\cdot \\
\cdot \\
v_{m-1} \\
v_m \\
\cdot \\
\cdot \\
\cdot \\
v_n
\end{array}
\equiv
\begin{array}{c}
\left( \begin{array}{cccc|cccc}
0 & 1 & 0 & \cdot & 0 & 0 & \cdot & \cdot & \cdot & 0 \\
\cdot & 0 & 1 & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\
\cdot & \cdot & \cdot & 0 & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\
\cdot & \cdot & \cdot & \cdot & 1 & 0 & \cdot & \cdot & \cdot & \cdot \\
0 & \cdot & \cdot & \cdot & 0 & 1 & 0 & \cdot & \cdot & 0 \\
\hline
1 & 0 & \cdot & \cdot & 0 & 0 & 1 & 0 & \cdot & \cdot \\
1 & 0 & \cdot & \cdot & 0 & 0 & 0 & 1 & 0 & \cdot \\
\cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & 0 \\
\cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & 1 \\
1 & 0 & \cdot & \cdot & 0 & 0 & \cdot & \cdot & \cdot & 0
\end{array} \right)
\end{array}$$

We define the characteristic polynomial of RLL(m,n) shift space is to be that of the adjacency matrix  $A(m, n)$  of the graph  $G(m, n)$ , which is calculated as follows:

$$\begin{aligned}
\chi_{A(m,n)}(t) &= \left| tE_{n+1} - A(m, n) \right| \\
&= \begin{array}{c} \left| \begin{array}{cccc|cccc}
t & -1 & 0 & \cdot & 0 & \cdot & \cdot & \cdot & \cdot & 0 \\
0 & t & -1 & \cdot & 0 & \cdot & \cdot & \cdot & \cdot & 0 \\
\cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\
0 & \cdot & \cdot & t & -1 & 0 & \cdot & \cdot & \cdot & \cdot \\
0 & \cdot & \cdot & \cdot & t & -1 & 0 & \cdot & \cdot & 0 \\
\hline
-1 & 0 & \cdot & \cdot & 0 & t & -1 & 0 & \cdot & \cdot \\
-1 & 0 & \cdot & \cdot & 0 & 0 & t & -1 & 0 & \cdot \\
\cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & 0 \\
\cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & t & -1 \\
-1 & 0 & \cdot & \cdot & 0 & 0 & \cdot & \cdot & \cdot & t
\end{array} \right| \\
&= \begin{array}{c} \left| \begin{array}{cccc|cccc}
0 & -1 & 0 & \cdot & 0 & \cdot & \cdot & \cdot & \cdot & 0 \\
t^2 & 0 & -1 & \cdot & 0 & \cdot & \cdot & \cdot & \cdot & 0 \\
\cdot & \cdot & t & -1 & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\
0 & \cdot & \cdot & t & -1 & 0 & \cdot & \cdot & \cdot & \cdot \\
0 & \cdot & \cdot & \cdot & t & -1 & 0 & \cdot & \cdot & 0 \\
\hline
-1 & 0 & \cdot & \cdot & 0 & t & -1 & 0 & \cdot & \cdot \\
-1 & 0 & \cdot & \cdot & 0 & 0 & t & -1 & 0 & \cdot \\
\cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & 0 \\
\cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & t & -1 \\
-1 & 0 & \cdot & \cdot & 0 & 0 & \cdot & \cdot & \cdot & t
\end{array} \right|
\end{array}
\end{aligned}$$

$$\begin{aligned}
 &= \left| \begin{array}{ccccc|ccccc} 0 & -1 & 0 & \cdot & 0 & 0 & \cdot & \cdot & \cdot & \cdot & 0 \\ 0 & 0 & -1 & & 0 & 0 & \cdot & \cdot & \cdot & \cdot & 0 \\ \cdot & \cdot & 0 & -1 & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ 0 & \cdot & \cdot & \cdot & -1 & 0 & \cdot & \cdot & \cdot & \cdot & \cdot \\ t^m & 0 & \cdot & \cdot & 0 & -1 & 0 & \cdot & \cdot & \cdot & 0 \\ \hline -1 & 0 & \cdot & \cdot & 0 & t & -1 & 0 & \cdot & \cdot & 0 \\ -1 & 0 & \cdot & \cdot & 0 & 0 & t & -1 & 0 & \cdot & \cdot \\ \cdot & \cdot & & & \cdot & \cdot & & & \cdot & \cdot & 0 \\ \cdot & \cdot & & & \cdot & \cdot & & & \cdot & t & -1 \\ -1 & 0 & \cdot & \cdot & 0 & 0 & \cdot & \cdot & \cdot & \cdot & t \end{array} \right| \\
 &= \left| \begin{array}{ccccc|ccccc} 0 & -1 & 0 & \cdot & 0 & 0 & \cdot & \cdot & \cdot & \cdot & 0 \\ 0 & 0 & -1 & & 0 & 0 & \cdot & \cdot & \cdot & \cdot & 0 \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ 0 & \cdot & \cdot & \cdot & -1 & 0 & \cdot & \cdot & \cdot & \cdot & \cdot \\ 0 & \cdot & \cdot & \cdot & 0 & -1 & 0 & \cdot & \cdot & \cdot & 0 \\ \hline t^{m+1} & -1 & 0 & \cdot & \cdot & 0 & t & -1 & 0 & \cdot & \cdot \\ -1 & 0 & \cdot & \cdot & 0 & 0 & t & -1 & 0 & \cdot & \cdot \\ \cdot & \cdot & & & \cdot & \cdot & & & \cdot & \cdot & 0 \\ \cdot & \cdot & & & \cdot & \cdot & & & \cdot & t & -1 \\ -1 & 0 & \cdot & \cdot & 0 & 0 & \cdot & \cdot & \cdot & \cdot & t \end{array} \right| \\
 &= \left| \begin{array}{ccccc|ccccc} 0 & -1 & 0 & \cdot & 0 & 0 & \cdot & \cdot & \cdot & \cdot & 0 \\ 0 & 0 & -1 & & 0 & 0 & \cdot & \cdot & \cdot & \cdot & 0 \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ 0 & \cdot & \cdot & \cdot & -1 & 0 & \cdot & \cdot & \cdot & \cdot & \cdot \\ 0 & \cdot & \cdot & \cdot & 0 & -1 & 0 & \cdot & \cdot & \cdot & 0 \\ \hline 0 & -1 & 0 & \cdot & \cdot & 0 & 0 & -1 & 0 & \cdot & \cdot \\ t(t^{m+1} - 1) & -1 & 0 & \cdot & \cdot & 0 & 0 & t & -1 & 0 & \cdot \\ \cdot & \cdot & & & \cdot & \cdot & \cdot & & \cdot & \cdot & 0 \\ \cdot & \cdot & & & \cdot & \cdot & \cdot & & \cdot & t & -1 \\ -1 & 0 & \cdot & \cdot & 0 & 0 & \cdot & \cdot & \cdot & \cdot & t \end{array} \right| \\
 &= \left| \begin{array}{ccccc|ccccc} 0 & -1 & 0 & \cdot & 0 & 0 & \cdot & \cdot & \cdot & \cdot & 0 \\ 0 & 0 & -1 & & 0 & 0 & \cdot & \cdot & \cdot & \cdot & 0 \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ 0 & \cdot & \cdot & \cdot & -1 & 0 & \cdot & \cdot & \cdot & \cdot & \cdot \\ 0 & \cdot & \cdot & \cdot & 0 & -1 & 0 & \cdot & \cdot & \cdot & 0 \\ \hline 0 & \cdot & \cdot & \cdot & 0 & 0 & -1 & 0 & \cdot & \cdot & 0 \\ 0 & \cdot & \cdot & \cdot & 0 & 0 & -1 & 0 & \cdot & \cdot & \cdot \\ \cdot & \cdot & & & \cdot & \cdot & & & \cdot & \cdot & 0 \\ 0 & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & -1 & \cdot \\ p(t) & 0 & \cdot & \cdot & 0 & 0 & \cdot & \cdot & \cdot & \cdot & 0 \end{array} \right| \\
 &= (-1)^{n+2} \times (-1)^n p(t) = p(t)
 \end{aligned}$$

where  $p(t) = t^{n+1} - \sum_{k=0}^{n-m} t^{n-m-k}$ .

### 3 The numbers of periodic points of RLL(m,n) shifts

First, we give the definitions of a periodic point, a cycle and the zeta function of a topological dynamical system. Let  $(M, \phi)$  be a topological dynamical system. We denote  $\phi^k$  the composition of  $\phi$  with itself  $k > 0$  times, and call it **k-th iteration** of  $\phi$ .

**Definition 3.1** A point  $x \in M$  is **periodic for  $\phi$**  if  $\phi^k(x) = x$  for some  $k \geq 1$ , and we say that  $x$  has

**period**  $k$  under  $\phi$ . If  $x$  is periodic, the smallest positive integer  $k$  for which  $\phi^k(x) = x$  is the **least period** of  $x$ . If  $\phi(x) = x$ , then  $x$  is called a **fixed point** for  $\phi$ .

**Definition 3.2** For a periodic point  $x_0$  for  $\phi$  of the least period  $k > 0$ , we call the subset  $C = \{x_0, \phi(x_0), \dots, \phi^{k-1}(x_0)\}$  of finite points of  $M$  a **cycle** of period  $k$  for  $\phi$ .

Let  $p_k(\phi)$  denote the number of periodic points of period  $k$ , and  $q_k(\phi)$  that of the least period  $k$ . For a shift space  $(X, \phi_X)$ , we write  $p_k(X)$  for  $p_k(\sigma_X)$  (resp.  $q_k(X)$  for  $q_k(\sigma_X)$ ). From the Möbius inversion formula ([2]),  $q_k(\phi)$  and  $p_k(\phi)$  are related as follows:

$$q_k(\phi) = \sum_{\ell|k} \mu\left(\frac{k}{\ell}\right) p_\ell(\phi)$$

where  $\mu$  is the Möbius function defined by

$$\mu(k') = \begin{cases} (-1)^r & \text{if } k' \text{ is the product of } r \text{ distinct primes,} \\ 0 & \text{if } k' \text{ contains a square factor,} \\ 1 & \text{if } k' = 1. \end{cases}$$

We are now going to calculate  $p_k(X(m, n))$  the number of periodic points of period  $k$  in the RLL  $(m, n)$  shift  $X(m, n)$  for  $k \geq 1$ . In what follows we write  $p_k(m, n)$  for  $p_k(X(m, n))$  for simplicity. We denote by  $\mathbb{Z}_{\geq 0}$  the set of all non-negative integers, and by  $\mathbb{Z}_{\geq 0}^{n-m+1}$  the product of  $n - m + 1$  copies of  $\mathbb{Z}_{\geq 0}$ . For a non-negative integer  $k$ , we define the subset  $D_k(m, n)$  of  $\mathbb{Z}_{\geq 0}^{n-m+1}$  by

$$D_k(m, n) = \left\{ (p_{m+1}, \dots, p_{n+1}) \in \mathbb{Z}_{\geq 0}^{n-m+1} \mid \sum_{i=1}^{n-m+1} (m+i)p_{m+i} = k \right\}.$$

Then, the number  $p_{k+1}(m, n)$  for  $k \geq 0$  is given as follows:

**Proposition 3.3**

$$(3.1) \quad p_{k+1}(m, n) = \begin{cases} 0 & (0 \leq k \leq m-1), \\ \sum_{(p_{m+1}, \dots, p_{n+1}) \in D_{k+1}(m, n)} \frac{(k+1)(p_{m+1} + \dots + p_{n+1} - 1)!}{p_{m+1}! \cdots p_{n+1}!} & (m \leq k), \end{cases}$$

where we understand that if  $D_{k+1}(m, n) = \emptyset$ , then the sum is equal to zero.

**Proof:** First, note that  $p_{k+1}(m, n)/k+1$  is the number of cycles of period  $k+1$  in  $X(m, n)$ , though, if a cycle has period  $k'+1$  with  $k+1 = \ell(k'+1)$  ( $\ell \geq 1$ ), then we should count this cycle as  $1/\ell$  of a cycle of period  $k+1$ . There is one-to-one correspondence between closed paths of length  $k+1$  in the graph  $G(m, n)$  and cycles of period  $k+1$  in the shift  $X(m, n)$  if we do not take account of which vertex and edge closed paths start at. Therefore, it suffices to count the number of closed paths starting at the vertex  $v_0$  of length  $k+1$  in the graph  $G(m, n)$ . In  $G(m, n)$  there are  $n - m + 1$  closed paths  $\pi_{m+1}, \dots, \pi_{n+1}$  starting at  $v_0$  specified by

$$\begin{cases} \pi_{m+1} & = e_0 \circ \cdots \circ e_{m-1} \circ f_m, \\ \pi_{m+2} & = e_0 \circ \cdots \circ e_{m-1} \circ e_m \circ f_{m+1}, \\ & \vdots \\ \pi_{n+1} & = e_0 \circ \cdots \circ e_{m-1} \circ e_m \circ \cdots \circ e_{n-1} \circ f_n. \end{cases}$$

We call these closed paths "fundamental paths" since every closed path  $\pi$  starting at  $v_0$  in  $G(m, n)$  can be expressed as

$$(3.2) \quad \pi = \pi_{i_1} \circ \pi_{i_2} \circ \cdots \circ \pi_{i_s},$$



where each  $\pi_{i_\alpha}$  ( $1 \leq \alpha \leq s$ ) in this expression is one of  $\pi_{m+1}, \dots, \pi_{n+1}$ . If we denote by  $p_{m+i}(\pi)$  the number of  $\pi_{m+i}$  which occurs in the expression in (3.2) for  $1 \leq i \leq n-m+1$ , then  $s = \sum_{i=1}^{n-m+1} p_{m+i}(\pi)$  and the length of the closed path  $\pi$  is  $\sum_{i=1}^{n-m+1} (m+i)p_{m+i}(\pi)$ . Note that, in the expression in (3.2), all of  $\pi_{i_1} \circ \pi_{i_2} \circ \dots \circ \pi_{i_s}$ ,  $\pi_{i_2} \circ \pi_{i_3} \circ \dots \circ \pi_{i_s} \circ \pi_{i_1}$ ,  $\dots$ ,  $\pi_{i_s} \circ \pi_{i_1} \circ \dots \circ \pi_{i_{s-1}}$  represent the same closed path in  $G(m, n)$ . To count the number of closed paths  $\pi$ 's which can be expressed as in (3.2) with  $p_{m+i}(\pi) = p_{m+i}$  for  $1 \leq i \leq n-m+1$  for a given  $(p_{m+1}, \dots, p_{n+1}) \in D_{k+1}(m, n)$ , we think of each  $p_{m+i}$  as the number of positions where the closed path  $\pi_{m+i}$  occurs in the expression in (3.2). Then the number we seek is

$$\begin{aligned} & \frac{1}{(p_{m+1} + \dots + p_{n+1})} \binom{p_{m+1} + \dots + p_{n+1}}{p_{m+2}} \binom{p_{m+1} + \dots + p_{n+1}}{p_{m+2}} \dots \binom{p_n + p_{n+1}}{p_n} \\ &= \frac{(p_{m+1} + \dots + p_{n+1} - 1)!}{p_{m+1}! \dots p_{n+1}!} \end{aligned}$$

Thus we have the equality in (3.1). ■

#### 4 Zeta functions of RLL(m,n) shifts

First, we give the definition of zeta function of a topological dynamical system.

**Definition 4.1** *Let  $(M, \phi)$  be a topological dynamical system for which  $p_k(\phi) < \infty$  for all  $k \geq 1$ . The zeta function  $\zeta_\phi(t)$  of  $(M, \phi)$  is defined by*

$$(4.1) \quad \zeta_\phi(t) = \exp \left( \sum_{k=1}^{\infty} \frac{p_k(\phi)}{k} t^k \right).$$

We know that if  $X$  is a shift of finite type, then there is an  $r \times r$  non-negative integer matrix  $A$  with  $X = X_A$  ([1], Theorem 2.3.2) and the zeta function of  $X_A$  is given by

$$(4.2) \quad \zeta_{\sigma_A}(t) = \frac{1}{t^r \chi_A(t^{-1})} = \frac{1}{\det(E_r - tA)},$$

where  $\sigma_A$  denotes the shift map of  $X_A$ , and  $\chi_A$  the characteristic polynomial of  $A$  ([1], Theorem 6.4.6). The equality in (4.2) follows from the definition of  $\zeta_\phi(t)$  and the fact that

$$p_k(\sigma_A) = \text{tr } A^k = \lambda_1^k + \lambda_2^k + \dots + \lambda_r^k$$

where  $\lambda_1, \dots, \lambda_r$  the root of  $\chi_A(t)$  listed with multiplicity ([1], Proposition 2.2.12).

Now, we calculate  $p_{k+1}(m, n)$  for  $k \geq 0$  by use of the zeta function of the shift dynamical system  $X_{G(m, n)}$ . Since the characteristic polynomial  $\chi_{A(m, n)}(t)$  of the adjacency matrix  $A(m, n)$  of the graph  $G(m, n)$  is specified by

$$\chi_{A(m, n)}(t) = t^{n+1} - (t^{n-m} + t^{n-m-1} + \dots + t + 1),$$

the zeta function  $\zeta_{\sigma_{A(m, n)}}(t)$  of  $X_{A(m, n)} = X_{G(m, n)}$  is given by

$$\zeta_{\sigma_{A(m, n)}}(t) = \frac{1}{t^{n+1} \chi_{A(m, n)}(t^{-1})} = \frac{1}{1 - (t^{m+1} + \dots + t^{n+1})}.$$

Therefore, by (4.1),

$$(4.3) \quad \sum_{k=0}^{\infty} \frac{p_{k+1}(m, n)}{k+1} t^{k+1} = \log \zeta_{\sigma_{A(m, n)}}(t) = -\log \{1 - (t^{m+1} + \dots + t^{n+1})\}.$$

We will calculate the Taylor's expansion of the R.H.S. of (4.3) at  $t = 0$ . Put

$$\varphi(t) = -\log\{1 - (t^{m+1} + \dots + t^{n+1})\},$$

$$g(t) = (m+1)t^m + \dots + (n+1)t^n, \quad \text{and}$$

$$f(t) = 1 - (t^{m+1} + \dots + t^{n+1}).$$

Then

$$\varphi'(t) = \frac{g(t)}{f(t)}, \quad \text{and}$$

$$\varphi^{(k+1)}(t) = \sum_{\ell=0}^k \binom{k}{\ell} \left(\frac{1}{f}\right)^{(k-\ell)}(t) g^{(\ell)}(t) \quad (k \geq 0),$$

and so

$$\varphi^{(k+1)}(0) = \sum_{\ell=0}^k \binom{k}{\ell} \left(\frac{1}{f}\right)^{(k-\ell)}(0) g^{(\ell)}(0) \quad (k \geq 0).$$

Since

$$g^{(\ell)}(0) = \begin{cases} (\ell+1)! & m \leq \ell \leq n, \\ 0 & \text{otherwise,} \end{cases}$$

we have

$$(4.4) \quad \varphi^{(k+1)}(0) = \begin{cases} 0 & (0 \leq k \leq m-1), \\ \sum_{\ell=m}^k \binom{k}{\ell} \left(\frac{1}{f}\right)^{(k-\ell)}(0) (\ell+1)! & (m \leq k \leq n-1) \\ \sum_{\ell=m}^n \binom{k}{\ell} \left(\frac{1}{f}\right)^{(k-\ell)}(0) (\ell+1)! & (n \leq k). \end{cases}$$

To know  $(1/f)^{(k-\ell)}(0)$ , we calculate the Taylor expansion of  $(1/f)(t)$  at  $t = 0$ , which is given by

$$(4.5) \quad \begin{aligned} \left(\frac{1}{f}\right)(t) &= \sum_{\alpha_0=0}^{\infty} (t^{n+1} + \dots + t^{m+1})^{\alpha_0} \\ &= \sum_{\alpha_0=0}^{\infty} \sum_{\alpha_1=0}^{\alpha_0} \sum_{\alpha_2=0}^{\alpha_0-\alpha_1} \dots \sum_{\alpha_{n-m}=0}^{\alpha_0-(\alpha_1+\dots+\alpha_{n-m-1})} \binom{\alpha_0}{\alpha_1} \binom{\alpha_0-\alpha_1}{\alpha_2} \dots \binom{\alpha_0-(\alpha_1+\dots+\alpha_{n-m-1})}{\alpha_{n-m}} \\ &\quad \times t^{\sum_{i=1}^{n-m} (m+i)\alpha_i + (n+1)(\alpha_0 - \sum_{i=1}^{n-m} \alpha_i)}. \\ &= \sum_{\alpha_0=0}^{\infty} \left\{ \sum_{\alpha_1=0}^{\alpha_0} \sum_{\alpha_2=0}^{\alpha_0-\alpha_1} \dots \sum_{\alpha_{n-m}=0}^{\alpha_0-(\alpha_1+\dots+\alpha_{n-m-1})} \frac{\alpha_0!}{\alpha_1! \alpha_2! \dots \alpha_{n-m}! (\alpha_0 - \alpha_1 - \dots - \alpha_{n-m})!} \right. \\ &\quad \left. \times t^{\sum_{i=1}^{n-m} (m+i)\alpha_i + (n+1)(\alpha_0 - \sum_{i=1}^{n-m} \alpha_i)} \right\}. \end{aligned}$$

Hence, if we put

$$D_k(m, n) = \left\{ (\alpha_1, \dots, \alpha_{n-m}, \alpha_{n-m+1}) \in \mathbb{Z}_{\geq 0}^{n-m+1} \mid \alpha_1 \geq 0, \dots, \alpha_{n-m+1} \geq 0, \sum_{i=1}^{n-m+1} (m+i)\alpha_i = k \right\},$$

then (4.5) can be written as

$$\left(\frac{1}{f}\right)(t) = \sum_{k=0}^{\infty} \left\{ \sum_{(\alpha_1, \dots, \alpha_{n-m}, \alpha_{n-m+1}) \in D_k(m, n)} \frac{(\alpha_1 + \dots + \alpha_{n-m+1})!}{\alpha_1! \dots \alpha_{n-m+1}!} \right\} t^k,$$

and so

$$\left(\frac{1}{f}\right)^{(k-\ell)}(0) = (k-\ell)! \sum_{(\alpha_1, \dots, \alpha_{n-m}, \alpha_{n-m+1}) \in D_{k-\ell}(m, n)} \frac{(\alpha_1 + \dots + \alpha_{n-m+1})!}{\alpha_1! \dots \alpha_{n-m+1}!}.$$

Hence, by (4.4),

$$(4.6) \quad \frac{\varphi^{(k+1)}(0)}{(k+1)!} = \begin{cases} 0 & (0 \leq k \leq m-1) \\ \frac{1}{k+1} \sum_{\ell=m}^n \sum_{(\alpha_1, \dots, \alpha_{n-m}, \alpha_{n-m+1}) \in D_{k-\ell}(m, n)} \frac{(\ell+1)(\alpha_1 + \dots + \alpha_{n-m+1})!}{\alpha_1! \dots \alpha_{n-m+1}!} & (m \leq k). \end{cases},$$

By the definition of  $\varphi(t)$ ,

$$\frac{\varphi^{(k+1)}(0)}{(k+1)!} = \frac{p_{k+1}(m, n)}{k+1}.$$

Therefor, by (4.6) and (3.1) we have the following equality:

$$(4.7) \quad \begin{aligned} & \sum_{(p_{m+1}, \dots, p_{n+1}) \in D_{k+1}(m, n)} \frac{(k+1)(p_{m+1} + \dots + p_{n+1} - 1)!}{p_{m+1}! \dots p_{n+1}!} \\ &= \sum_{\ell=m}^n \sum_{(p_{m+1}, \dots, p_{n+1}) \in D_{k-\ell}(m, n)} \frac{(\ell+1)(p_{m+1} + \dots + p_{n+1})!}{p_{m+1}! \dots p_{n+1}!} \quad (k \geq m) \end{aligned}$$

## 5 A formula in combinatorics

We will generalize the formula in (4.7). Let  $a_1, \dots, a_s$  ( $s \geq 1$ ) be positive integers with  $a_1 < a_2 < \dots < a_s$ , and  $k$  a non-negative integer. We define  $D_k(a_1, \dots, a_s)$  by

$$D_k(a_1, \dots, a_s) = \left\{ (p_1, \dots, p_s) \in \mathbb{Z}_{\geq 0}^s \mid \sum_{i=1}^s (a_i + 1)p_i = k \right\}.$$

When  $s = n - m + 1$  and  $a_1 = m, a_2 = m + 1, \dots, a_{n-m+1} = n$ ,  $D_k(a_1, \dots, a_s)$  is nothing but  $D_k(m, n)$  defined before. With this notation, we have:

**Theorem 5.1**

$$(5.1) \quad \begin{aligned} & \sum_{(p_1, \dots, p_s) \in D_{k+1}(a_1, \dots, a_s)} \frac{(k+1)(p_1 + \dots + p_s - 1)!}{p_1! \dots p_s!} \\ &= \sum_{i=1}^s \sum_{(p_1, \dots, p_s) \in D_{k-a_i}(a_1, \dots, a_s)} \frac{(a_i + 1)(p_1 + \dots + p_s)!}{p_1! \dots p_s!} \quad (k \geq a_1) \end{aligned}$$

**Proof:** We use the induction on  $s$ .

(I) In the case  $s = 1$ :  $D_{k+1}(\mathbf{a}_1)$  ( $k \geq \mathbf{a}_1$ ) is not empty if and only if  $k+1$  is a multiple of  $\mathbf{a}_1 + 1$ . If this is the case, we have

$$\frac{k+1}{p_1} = \mathbf{a}_1 + 1$$

for  $p_1 \in D_{k+1}(\mathbf{a}_1)$  and the map which assigns  $p_1$  to  $p_1 - 1$  gives a one-to-one correspondence from  $D_{k+1}(\mathbf{a}_1)$  to  $D_{k-\mathbf{a}_1}(\mathbf{a}_1)$ . Hence the equality in (5.1) holds.

(II) In the case  $s \geq 2$ : We assume that the equality in (5.1) holds for  $s - 1$ . We put

$$S = \sum_{(p_1, \dots, p_s) \in D_{k+1}(\mathbf{a}_1, \dots, \mathbf{a}_s)} \frac{(k+1)(p_1 + \dots + p_s - 1)!}{p_1! \cdots p_s!}$$

For  $i$  with  $1 \leq i \leq s$ ,

$$\begin{aligned} S &= \sum_{\substack{(p_1, \dots, p_s) \in D_{k+1}(\mathbf{a}_1, \dots, \mathbf{a}_s) \\ p_i \geq 1}} \frac{(k+1)(p_1 + \dots + p_s - 1)!}{p_1! \cdots p_s!} \\ &+ \sum_{\substack{(p_1, \dots, p_s) \in D_{k+1}(\mathbf{a}_1, \dots, \mathbf{a}_s) \\ p_i = 0}} \frac{(k+1)(p_1 + \dots + \check{p}_i + \dots + p_s - 1)!}{p_1! \cdots \check{p}_i! \cdots p_s!} \end{aligned}$$

where  $\check{p}_i$  and  $\check{p}_i!$  denotes deleting the symbols  $p_i$  and  $p_i!$ . Hence, we have

$$(5.2) \quad S = \frac{1}{s} \left\{ \sum_{i=1}^s \sum_{\substack{(p_1, \dots, p_s) \in D_{k+1}(\mathbf{a}_1, \dots, \mathbf{a}_s) \\ p_i \geq 1}} \frac{(k+1)(p_1 + \dots + p_s - 1)!}{p_1! \cdots p_s!} + \sum_{i=1}^s \sum_{\substack{(p_1, \dots, p_s) \in D_{k+1}(\mathbf{a}_1, \dots, \mathbf{a}_s) \\ p_i = 0}} \frac{(k+1)(p_1 + \dots + \check{p}_i + \dots + p_s - 1)!}{p_1! \cdots \check{p}_i! \cdots p_s!} \right\}$$

Since each  $(p_1, \dots, p_s) \in D_{k+1}(\mathbf{a}_1, \dots, \mathbf{a}_s)$  satisfies

$$\sum_{j=1}^s (\mathbf{a}_j + 1)p_j = k+1 \quad \text{and so,} \quad \frac{k+1}{p_i} = (\mathbf{a}_i + 1) + \sum_{\substack{j=1 \\ j \neq i}}^s (\mathbf{a}_j + 1) \frac{p_j}{p_i}$$

for every  $i$  with  $1 \leq i \leq s$ , the first term in the braces in (5.2) is transformed as follows:

$$\begin{aligned}
& \sum_{i=1}^s \sum_{\substack{(p_1, \dots, p_s) \in \mathcal{D}_{k+1}(\mathbf{a}_1, \dots, \mathbf{a}_s) \\ p_i \geq 1}} \frac{(k+1)(p_1 + \dots + p_s - 1)!}{p_1! \cdots p_s!} \\
&= \sum_{i=1}^s \sum_{\substack{(p_1, \dots, p_s) \in \mathcal{D}_{k+1}(\mathbf{a}_1, \dots, \mathbf{a}_s) \\ p_i \geq 1}} \frac{k+1}{p_i} \frac{\{(p_1 + \dots + (p_i - 1) + \dots + p_s)\}!}{p_1! \cdots (p_i - 1)! \cdots p_s!} \\
&= \sum_{i=1}^s \sum_{\substack{(p_1, \dots, p_s) \in \mathcal{D}_{k+1}(\mathbf{a}_1, \dots, \mathbf{a}_s) \\ p_i \geq 1}} (a_i + 1) \frac{\{(p_1 + \dots + (p_i - 1) + \dots + p_s)\}!}{p_1! \cdots (p_i - 1)! \cdots p_s!} \\
(5.3) \quad &+ \sum_{i=1}^s \sum_{\substack{(p_1, \dots, p_s) \in \mathcal{D}_{k+1}(\mathbf{a}_1, \dots, \mathbf{a}_s) \\ p_i \geq 1}} \sum_{\substack{j=1 \\ j \neq i}}^s (a_j + 1) \frac{p_j \{(p_1 + \dots + (p_i - 1) + \dots + p_s)\}!}{p_i p_1! \cdots (p_i - 1)! \cdots p_s!} \\
&= \sum_{i=1}^s \sum_{(p_1, \dots, p_s) \in \mathcal{D}_{k-a_i}(\mathbf{a}_1, \dots, \mathbf{a}_s)} (a_i + 1) \frac{(p_1 + \dots + p_s)!}{p_1! \cdots p_s!} \\
&+ \sum_{i=1}^s \sum_{\substack{(p_1, \dots, p_s) \in \mathcal{D}_{k+1}(\mathbf{a}_1, \dots, \mathbf{a}_s) \\ p_i \geq 1}} \sum_{\substack{j=1 \\ j \neq i}}^s (a_j + 1) \frac{p_j \{(p_1 + \dots + (p_i - 1) + \dots + p_s)\}!}{p_i p_1! \cdots (p_i - 1)! \cdots p_s!}
\end{aligned}$$

On the other hand, by the induction hypothesis the second term in the braces in (5.2) is transformed as follows:

$$\begin{aligned}
& \sum_{i=1}^s \sum_{\substack{(p_1, \dots, p_i, \dots, p_s) \in \mathcal{D}_{k+1}(\mathbf{a}_1, \dots, \mathbf{a}_s) \\ p_i = 0}} (k+1) \frac{(p_1 + \dots + \check{p}_i + \dots + p_s - 1)!}{p_1! \cdots \check{p}_i! \cdots p_s!} \\
(5.4) \quad &= \sum_{i=1}^s \sum_{\substack{j=1 \\ j \neq i}}^s \sum_{\substack{(p_1, \dots, p_s) \in \mathcal{D}_{k-a_j}(\mathbf{a}_1, \dots, \mathbf{a}_s) \\ p_i = 0}} (a_j + 1) \frac{(p_1 + \dots + \check{p}_i + \dots + p_s)!}{p_1! \cdots \check{p}_i! \cdots p_s!}.
\end{aligned}$$

We claim that

$$\begin{aligned}
& \sum_{i=1}^s \sum_{\substack{(p_1, \dots, p_s) \in \mathcal{D}_{k+1}(\mathbf{a}_1, \dots, \mathbf{a}_s) \\ p_i \geq 1}} \sum_{\substack{j=1 \\ j \neq i}}^s (a_j + 1) \frac{p_j \{(p_1 + \dots + (p_i - 1) + \dots + p_s)\}!}{p_i p_1! \cdots (p_i - 1)! \cdots p_s!} \\
(5.5) \quad &+ \sum_{i=1}^s \sum_{\substack{j=1 \\ j \neq i}}^s \sum_{\substack{(p_1, \dots, p_s) \in \mathcal{D}_{k-a_j}(\mathbf{a}_1, \dots, \mathbf{a}_s) \\ p_i = 0}} (a_j + 1) \frac{(p_1 + \dots + \check{p}_i + \dots + p_s)!}{p_1! \cdots \check{p}_i! \cdots p_s!} \\
&= (s-1) \sum_{i=1}^s \sum_{(p_1, \dots, p_s) \in \mathcal{D}_{k-a_i}(\mathbf{a}_1, \dots, \mathbf{a}_s)} (a_i + 1) \frac{(p_1 + \dots + p_s)!}{p_1! \cdots p_s!}.
\end{aligned}$$

Indeed, this can be proved as follows:

$$\begin{aligned}
& \text{The first term on the L.H.S. in (5.5)} \\
&= \sum_{i=1}^s \sum_{\substack{j=1 \\ j \neq i}}^s \sum_{\substack{(\mathbf{p}_1, \dots, \mathbf{p}_s) \in \mathcal{D}_{k+1}(\mathbf{a}_1, \dots, \mathbf{a}_s) \\ \mathbf{p}_i \geq 1}} (\mathbf{a}_j + 1) \frac{\mathbf{p}_j \{(\mathbf{p}_1 + \dots + (\mathbf{p}_i - 1) + \dots + \mathbf{p}_s)\}}{\mathbf{p}_i \mathbf{p}_1! \dots (\mathbf{p}_i - 1)! \dots \mathbf{p}_s!} \\
&= \sum_{i=1}^s \sum_{\substack{j=1 \\ j \neq i}}^s \sum_{\substack{(\mathbf{p}_1, \dots, \mathbf{p}_s) \in \mathcal{D}_{k+1}(\mathbf{a}_1, \dots, \mathbf{a}_s) \\ \mathbf{p}_i \geq 1, \mathbf{p}_j \geq 1}} (\mathbf{a}_j + 1) \frac{\{(\mathbf{p}_1 + \dots + (\mathbf{p}_j - 1) + \dots + \mathbf{p}_s)\}}{\mathbf{p}_1! \dots (\mathbf{p}_j - 1)! \dots \mathbf{p}_s!} \\
&= \sum_{i=1}^s \sum_{\substack{j=1 \\ j \neq i}}^s \sum_{\substack{(\mathbf{p}_1, \dots, \mathbf{p}_s) \in \mathcal{D}_{k-a_j}(\mathbf{a}_1, \dots, \mathbf{a}_s) \\ \mathbf{p}_i \geq 1}} (\mathbf{a}_j + 1) \frac{(\mathbf{p}_1 + \dots + \mathbf{p}_s)!}{\mathbf{p}_1! \dots \mathbf{p}_s!}
\end{aligned}$$

Hence:

$$\begin{aligned}
& \text{The L.H.S in (5.5)} \\
&= \sum_{i=1}^s \sum_{\substack{j=1 \\ j \neq i}}^s \sum_{\substack{(\mathbf{p}_1, \dots, \mathbf{p}_s) \in \mathcal{D}_{k-a_j}(\mathbf{a}_1, \dots, \mathbf{a}_s) \\ \mathbf{p}_i \geq 1}} (\mathbf{a}_j + 1) \frac{(\mathbf{p}_1 + \dots + \mathbf{p}_s)!}{\mathbf{p}_1! \dots \mathbf{p}_s!} \\
&\quad + \sum_{i=1}^s \sum_{\substack{j=1 \\ j \neq i}}^s \sum_{\substack{(\mathbf{p}_1, \dots, \mathbf{p}_s) \in \mathcal{D}_{k-a_j}(\mathbf{a}_1, \dots, \mathbf{a}_s) \\ \mathbf{p}_i = 0}} (\mathbf{a}_j + 1) \frac{(\mathbf{p}_1 + \dots + \check{\mathbf{p}}_i + \dots + \mathbf{p}_s)!}{\mathbf{p}_1! \dots \check{\mathbf{p}}_i! \dots \mathbf{p}_s!} \\
&= \sum_{i=1}^s \sum_{\substack{j=1 \\ j \neq i}}^s \sum_{\substack{(\mathbf{p}_1, \dots, \mathbf{p}_s) \in \mathcal{D}_{k-a_j}(\mathbf{a}_1, \dots, \mathbf{a}_s) \\ \mathbf{p}_i \geq 1}} (\mathbf{a}_j + 1) \frac{(\mathbf{p}_1 + \dots + \mathbf{p}_s)!}{\mathbf{p}_1! \dots \mathbf{p}_s!} \\
&= \sum_{i=1}^s \sum_{\substack{j=1 \\ j \neq i}}^s \sum_{\substack{(\mathbf{p}_1, \dots, \mathbf{p}_s) \in \mathcal{D}_{k-a_j}(\mathbf{a}_1, \dots, \mathbf{a}_s) \\ \mathbf{p}_i \geq 1}} (\mathbf{a}_j + 1) \frac{(\mathbf{p}_1 + \dots + \mathbf{p}_s)!}{\mathbf{p}_1! \dots \mathbf{p}_s!} \\
&\quad - \sum_{i=1}^s \sum_{\substack{(\mathbf{p}_1, \dots, \mathbf{p}_s) \in \mathcal{D}_{k-a_i}(\mathbf{a}_1, \dots, \mathbf{a}_s) \\ \mathbf{p}_i = 0}} (\mathbf{a}_i + 1) \frac{(\mathbf{p}_1 + \dots + \mathbf{p}_s)!}{\mathbf{p}_1! \dots \mathbf{p}_s!} \\
&= (s-1) \sum_{i=1}^s \sum_{\substack{(\mathbf{p}_1, \dots, \mathbf{p}_s) \in \mathcal{D}_{k-a_i}(\mathbf{a}_1, \dots, \mathbf{a}_s) \\ \mathbf{p}_i \geq 1}} (\mathbf{a}_i + 1) \frac{(\mathbf{p}_1 + \dots + \mathbf{p}_s)!}{\mathbf{p}_1! \dots \mathbf{p}_s!}.
\end{aligned}$$

Thus, the equality in (5.5) holds. Consequently, by (5.2), (5.3), (5.4) and (5.5), we obtain the equality in (5.1). ■

## 6 RLL( $\mathbf{a}_1, \dots, \mathbf{a}_s$ ) shifts

The number on the L.H.S. in (5.1) relates to the number of  $(k+1)$  cycles of a certain shift dynamical system. For positive integers  $\mathbf{a}_1, \dots, \mathbf{a}_s$  ( $s \geq 1$ ) with  $\mathbf{a}_1 < \mathbf{a}_2 < \dots < \mathbf{a}_s$ , we define the  $(\mathbf{a}_1, \dots, \mathbf{a}_s)$  **run-length limited shift**, denoted by  $\text{RLL}(\mathbf{a}_1, \dots, \mathbf{a}_s)$ , or  $\mathcal{X}(\mathbf{a}_1, \dots, \mathbf{a}_s)$ , to be the shift space associated to the labeled graph in Figure 6.1. We denote by  $G(\mathbf{a}_1, \dots, \mathbf{a}_s)$  the underlying graph of the labeled one in Figure 6.1, by  $A(\mathbf{a}_1, \dots, \mathbf{a}_s)$  the adjacency matrix of the

graph  $G(\mathbf{a}_1, \dots, \mathbf{a}_s)$  and by  $X_{G(\mathbf{a}_1, \dots, \mathbf{a}_s)}$ , or  $X_{A(\mathbf{a}_1, \dots, \mathbf{a}_s)}$ , the edge shift associated to  $G(\mathbf{a}_1, \dots, \mathbf{a}_s)$ . As in the case of RLL( $m, n$ ) shift,  $\mathcal{X}(\mathbf{a}_1, \dots, \mathbf{a}_s)$  is conjugate to  $X_{G(\mathbf{a}_1, \dots, \mathbf{a}_s)}$  as a shift space. The number on the L.H.S. in (5.1) is equal to  $\mathbf{p}_{k+1}(\mathcal{X}(\mathbf{a}_1, \dots, \mathbf{a}_s))$ , the number of periodic points of period  $k+1$  in  $\mathcal{X}(\mathbf{a}_1, \dots, \mathbf{a}_s)$ . The adjacency matrix  $A(\mathbf{a}_1, \dots, \mathbf{a}_s)$  is given by

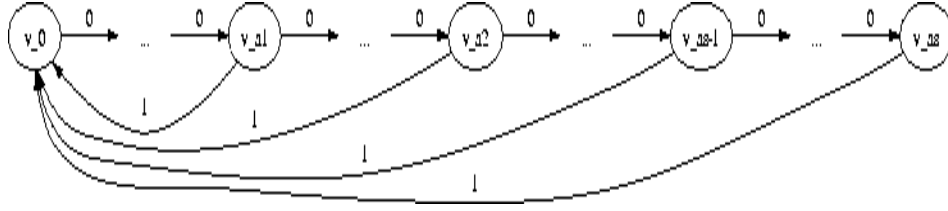


Figure 6.1:  $X(a_1, \dots, a_s)$

$$A(a_1, \dots, a_s) = \begin{matrix} & v_0 & v_1 & \dots & v_{a_1-1} & v_{a_1} & \dots & \dots & v_{a_s} \\ \begin{matrix} v_0 \\ v_1 \\ \cdot \\ \cdot \\ v_{a_1-1} \\ v_{a_1} \\ v_{a_1+1} \\ \cdot \\ \cdot \\ v_{a_2-1} \\ v_{a_2} \\ v_{a_2+1} \\ \cdot \\ \cdot \\ v_{a_s-1} \\ v_{a_s} \end{matrix} & \left( \begin{array}{cccc|cccc} 0 & 1 & 0 & \dots & 0 & 0 & 0 & \dots & 0 \\ \cdot & \cdot & & & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & & & & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & & & & 1 & 0 & \cdot & \cdot & \cdot \\ 0 & \cdot & \cdot & \cdot & 0 & 1 & 0 & \cdot & 0 \\ \hline 1 & 0 & \cdot & \cdot & 0 & 0 & 1 & \cdot & 0 \\ 0 & 0 & \cdot & \cdot & 0 & 0 & 0 & 1 & 0 \\ \cdot & & & & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & & & & \cdot & \cdot & \cdot & \cdot & \cdot \\ 0 & 0 & & & \cdot & \cdot & \cdot & \cdot & 0 \\ v_{a_2} & 1 & 0 & & \cdot & \cdot & \cdot & \cdot & 0 \\ v_{a_2+1} & 0 & 0 & & \cdot & \cdot & \cdot & \cdot & 0 \\ \cdot & \cdot & & & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & & & \cdot & \cdot & \cdot & \cdot & \cdot \\ v_{a_s-1} & 0 & & & \cdot & \cdot & \cdot & \cdot & 1 \\ v_{a_s} & 1 & 0 & \cdot & 0 & \cdot & \cdot & \cdot & 0 \end{array} \right) \end{matrix}$$

and so the characteristic polynomial  $\chi_{A(a_1, \dots, a_s)}(t)$  of  $A(a_1, \dots, a_s)$  is given by

$$\chi_{A(a_1, \dots, a_s)}(t) = \left| tE_{a_s+1} - A(a_1, \dots, a_s) \right| = t^{a_s+1} - (t^{a_s-a_1} + t^{a_s-a_2} + \dots + t^{a_s-a_{s-1}} + 1).$$

Hence the zeta function  $\zeta_{\sigma_{A(a_1, \dots, a_s)}}(t)$  of  $X_{A(a_1, \dots, a_s)} = X_{G(a_1, \dots, a_s)}$  is given by

$$\zeta_{A(a_1, \dots, a_s)}(t) = \frac{1}{t^{a_s+1} \chi_{A(a_1, \dots, a_s)}(t^{-1})} = \frac{1}{1 - (t^{a_1+1} + \dots + t^{a_s+1})}.$$

As in the case of RLL(m, n) shift, we can prove the equality in (5.1) by use of the identity

$$(6.1) \quad \sum_{k=0}^{\infty} \frac{p_{k+1}(X(a_1, \dots, a_s))}{k+1} t^{k+1} = \log \zeta_{\sigma_{A(a_1, \dots, a_s)}}(t) = -\log \{1 - (t^{a_1+1} + \dots + t^{a_s+1})\}.$$

Notice that if we want to prove the equality in (4.7) directly, not using the zeta function of  $X_{G(m,n)}$ , we need to generalize it to that of the form in (5.1), since we cannot apply the induction argument to the equality in (4.7) to prove it.

## References

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